Package ‘mrf2d’

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Type Package

Title Markov Random Field Models for Image Analysis

Version 0.5

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Description Model fitting, sampling and visualization for the (Hidden) Markov Random Field model with pairwise interactions and general interaction structure from Freguglia, Garcia & Bicas (2020) <doi:10.1002/env.2613>, which has many popular models used in 2-dimensional lattices as particular cases, like the Ising Model and Potts Model.

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Encoding UTF-8

LazyData true

Imports Rcpp (>= 1.0.1), dplyr(>= 0.8.1), tidyr, methods, ggplot2, Rdpack

Depends R (>= 3.5.0)

LinkingTo Rcpp, RcppArmadillo

RdMacros Rdpack

RoxygenNote 7.1.1

Suggests testthat (>= 2.1.0), covr, knitr, rmarkdown, glue

VignetteBuilder knitr


BugReports https://github.com/Freguglia/mrf2d/issues

NeedsCompilation yes

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Repository CRAN

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Description

fourier_2d() and polynomial_2d() creates a list of basis functions to be used as the fixed effect in fit_ghm.

Usage

fourier_2d(max_freqs, lattice_dim)

polynomial_2d(poly_deg, lattice_dim)

Arguments

max_freqs A length 2 numeric vector with maximum frequencies considered (x-axis and y-axis direction, respectively).
lattice_dim A length 2 numeric vector with lattice dimensions (N,M) to be used.
poly_deg A length 2 numeric vector with degrees of the bivariate polynomial to be considered.
Details

fourier_2d() is for 2-dimensional Fourier transform.

Value

A list of functions.

Author(s)

Victor Freguglia

See Also

A paper with detailed description of the package can be found at https://arxiv.org/abs/2006.00383

Examples

fourier_2d(c(10,10), dim(Z_potts))
polynomial_2d(c(3,3), dim(Z_potts))

bold5000

**BOLD5000 neuroimaging data**

Description

An image extracted from the "BOLD5000" open dataset. It was read from the file in path BOLD5000/DS001499/SUB-CS12/SES-16/ANAT/SUB-CS12_SES-16_T1W.NII.GZ, available at the OpenNeuro platform (https://openneuro.org/datasets/ds001499/versions/1.3.0).

Usage

bold5000

Format

An object of class matrix (inherits from array) with 176 rows and 256 columns.

Details

The file was read using the oro.nifti package and the image was extracted from the matrix in slice 160.

References

See Also

A paper with detailed description of the package can be found at https://arxiv.org/abs/2006.00383

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**cpmrf2d**

*Conditional probabilities in a pixel position*

**Description**

Computes the vector of conditional probabilities for a pixel position given a field, an interaction structure and a parameter array.

**Usage**

```r
cp_mrf2d(Z, mrfi, theta, pos)
```

**Arguments**

- `Z` A matrix with integers in \{0,...,C\}.
- `mrfi` A `mrfi` object representing the interaction structure.
- `theta` A 3-dimensional array describing potentials. Slices represent interacting positions, rows represent pixel values and columns represent neighbor values. As an example: `theta[1,3,2]` has the potential for the pair of values 0,2 observed in the second relative position of `mrfi`.
- `pos` Length-2 vector with the position to compute conditional probabilities in.

**Value**

A numeric vector with the conditional probabilities.

**Author(s)**

Victor Freguglia

See Also

A paper with detailed description of the package can be found at https://arxiv.org/abs/2006.00383

**Examples**

```r
cp_mrf2d(Z_potts, mrfi(1), theta_potts, c(57,31))
cp_mrf2d(Z_potts, mrfi(1), theta_potts*0.1, c(57,31))
```
Description

mrf2d contains a set of simulated fields to illustrate its usage.

field1 A binary field sampled from a sparse interaction structure: mrfi(1) + c(4,4)

hfield1 A continuous valued field, obtained by Gaussian mixture driven by field1.

Usage

field1
hfield1

Format

An object of class matrix (inherits from array) with 150 rows and 150 columns.

An object of class matrix (inherits from array) with 150 rows and 150 columns.

Author(s)

Victor Freguglia

dplot

Plotting functions for lattice data

Description

dplot() and cplot() are functions for plotting lattice data. They are an alternative to base R’s image() function using ggplot2 instead. dplot is used for discrete data and cplot for continuous data, they only differ in the fact that pixel values are treated as a factor in dplot, therefore, a discrete scale is used.

Usage

dplot(Z, legend = FALSE)

cplot(Y, legend = TRUE)

Arguments

Z A matrix object with integers only.
legend logical indicating whether a legend should be included or not.
Y A matrix object with continuous values.
Details
Since returns a ggplot object, other layers can be added to it using the usual ggplot2 syntax in order to modify any aspect of the plot.
The data frame used to create the object has columns named x, y and value, which are mapped to x, y and fill, respectively, used with geom_tile().

Value
a ggplot object.

Author(s)
Victor Freguglia

Examples
# Plotting discrete data
dplot(Z_potts)

#Making it continuous
cplot(Z.potts + rnorm(length(Z.potts)))

#Adding extra ggplot layers
library(ggplot2)
dplot(Z.potts) + ggtitle("This is a title")
dplot(Z.potts, legend = TRUE) + scale_fill_brewer(palette = "Set1")

fit_ghm

EM estimation for Gaussian Hidden Markov field

Description
fit_ghm fits a Gaussian Mixture model with hidden components driven by a Markov random field with known parameters. The inclusion of a linear combination of basis functions as a fixed effect is also possible.
The algorithm is a modification of of (Zhang et al. 2001), which is described in (Freguglia et al. 2020).

Usage
fit_ghm(
  Y,
  mrfi,
  theta,
  fixed_fn = list(),
)
fit_ghm

```r
equal_vars = FALSE,
init_mus = NULL,
init_sigmas = NULL,
maxiter = 100,
max_dist = 10^-3,
icm_cycles = 6,
verbose = interactive(),
qr = NULL
```

**Arguments**

- **Y**
  A matrix of observed (continuous) pixel values.

- **mrfi**
  A mrfi object representing the interaction structure.

- **theta**
  A 3-dimensional array describing potentials. Slices represent interacting positions, rows represent pixel values and columns represent neighbor values. As an example: `theta[1,3,2]` has the potential for the pair of values 0.2 observed in the second relative position of `mrfi`.

- **fixed_fn**
  A list of functions `fn(x,y)` to be considered as a fixed effect. See `basis_functions`.

- **equal_vars**
  Logical indicating if the mixture model has the same variances in all mixture components.

- **init_mus**
  Optional. A numeric with length (C+1) with the initial mean estimate for each component.

- **init_sigmas**
  Optional. A numeric with length (C+1) with initial sample deviation estimate for each component.

- **maxiter**
  The maximum number of iterations allowed. Defaults to 100.

- **max_dist**
  Defines a stopping condition. The algorithm stops if the maximum absolute difference between parameters of two consecutive iterations is less than `max_dist`.

- **icm_cycles**
  Number of steps used in the Iterated Conditional Modes algorithm executed in each interaction. Defaults to 6.

- **verbose**
  Logical indicating whether to print the progress or not.

- **qr**
  The QR decomposition of the design matrix. Used internally.

**Details**

If either `init_mus` or `init_sigmas` is `NULL` an EM algorithm considering an independent uniform distribution for the hidden component is fitted first and its estimated means and sample deviations are used as initial values. This is necessary because the algorithm may not converge if the initial parameter configuration is too far from the maximum likelihood estimators.

`max_dist` defines a stopping condition. The algorithm will stop if the maximum absolute difference between ($\mu$ and $\sigma$) parameters in consecutive iterations is less than `max_dist`. 
Value

A hmrfout containing:

- `par`: A `data.frame` with \( \mu \) and \( \sigma \) estimates for each component.
- `fixed`: A matrix with the estimated fixed effect in each pixel.
- `Z_pred`: A matrix with the predicted component (highest probability) in each pixel.
- `predicted`: A matrix with the fixed effect + the \( \mu \) value for the predicted component in each pixel.
- `iterations`: Number of EM iterations done.

Author(s)

Victor Freguglia

References


See Also


Examples

```r
# Sample a Gaussian mixture with components given by Z_potts
# mean values are 0, 1 and 2 and a linear effect on the x-axis.

set.seed(2)
Y <- Z_potts + rnorm(length(Z_potts), sd = 0.4) +
    (row(Z_potts) - mean(row(Z_potts)))*0.01
# Check what the data looks like
cplot(Y)

fixed <- polynomial_2d(c(1,0), dim(Y))
fit <- fit_ghm(Y, mrfi = mrfi(1), theta = theta_potts, fixed_fn = fixed)
fit$par
cplot(fit$fixed)
```
**fit_pl**

*Maximum Pseudo-likelihood fitting of MRFs on 2d lattices.*

**Description**


**Usage**

```r
fit_pl(
  Z,
  mrfi,
  family = "onepar",
  init = 0,
  optim_args = list(method = "BFGS"),
  return_optim = FALSE
)
```

**Arguments**

- `Z` 
  A matrix object containing the observed MRF. NA values can be used to create a subregion of the lattice for non-rectangular data.

- `mrfi` 
  A `mrfi` object representing the interaction structure.

- `family` 
  The family of parameter restrictions to potentials. Families are: 'onepar', 'oneeach', 'absdif', 'dif' or 'free'. See `mrf2d-familiy`.

- `init` 
  The initial value to be used in the optimization. It can be:
  - A valid array of parameter values according to `family`.
  - 0. If set to 0 an array with '0" in all entries is created.

- `optim_args` 
  Additional parameters passed to `optim()`.

- `return_optim` 
  logical indicating whether information from the `optim()` call are returned.

**Value**

An object of class `mrfout` with elements:

- `theta`: The estimated array of potential values.
- `mrfi`: The interaction structure considered.
- `family`: The parameter restriction family considered.
- `method`: The estimation method ("Pseudolikelihood").
- `value`: The optimal pseudo-likelihood value.
- `opt.xxx` (if `return_optim` is TRUE): Information returned by the `optim()` function used for the optimization.
Author(s)
Victor Freguglia

See Also
A paper with detailed description of the package can be found at https://arxiv.org/abs/2006.00383

Examples

```r
fit_pl(Z_potts, mrfi(1), family = "onepar")
fit_pl(Z_potts, mrfi(1), family = "oneeach")
fit_pl(Z_potts, mrfi(2), family = "onepar")
```

Description
Estimates the parameters of a MRF by successively sampling from a parameter configuration and updating it by comparing the sufficient statistics of the sampled field and the observed field. This method aims to find the parameter value where the gradient of the likelihood function is equal to zero.

Usage

```r
fit_sa(
    Z,  # A matrix object containing the observed MRF. NA values can be used to create a subregion of the lattice for non-rectangular data.
    mrfi,  # A mrfi object representing the interaction structure.
    family = "onepar",  # The family of parameter restrictions to potentials. Families are: 'onepar', 'oneeach', 'absdif', 'dif' or 'free'. See mrf2d-family.
    gamma_seq,  # The sequence of gamma values used to update the parameter values.
    init = 0,  # The initial value of the parameter configuration.
    cycles = 5,  # The number of cycles to perform.
    refresh_each = length(gamma_seq) + 1,  # The refresh frequency.
    refresh_cycles = 60,  # The refresh cycle length.
    verbose = interactive()  # Whether to print progress messages.
)
```
gamma_seq  A numeric vector with the sequence of constants used in each step $\gamma_t$.

init  The initial value to be used in the optimization. It can be:
- A valid array of parameter values according to family.
- 0. If set to 0 an array with ‘0’ in all entries is created.

cycles  The number of updates to be done (for each each pixel).

refresh_each  An integer with the number of iterations taken before a complete refresh (restart from a random state). This prevents the sample from being stuck in a mode for too long. Defaults to $\text{length}(\text{gamma_seq}) + 1$ (no refresh happens).

refresh_cycles  An integer indicating how many Gibbs Sampler cycles are performed when a refresh happens. Larger is usually better, but slower.

verbose  logical indicating whether the iteration number is printed during execution.

Details

The stochastic approximation method consists of, given an observed field $Z$, and a starting parameters configuration $\theta_0$, successively sample a field $Z_t$ from the current parameter configuration and estimate the direction of the gradient of the likelihood function by comparing the sufficient statistics in the current sample and the observed field.

The solution is updated by moving in the estimated direction with a predefined step size $\gamma_t$, a new field $Z_{t+1}$ is sampled using the new parameter configuration and $Z_t$ as an initial value, and the process is repeated.

$$\theta_{t+1} = \theta_t - \gamma_t (T(Z_t) - T(Z)),$$

where $T(Z)$ is the sufficient statistics for the reference field, $T(Z_t)$ is the sufficient statistics for a field sampled from $\theta_t$.

gamma_seq is normalized internally by diving values by $\text{length}(Z)$, so the choice of the sequence is invariant to the lattice dimensions. Typically, a sequence like $\text{seq}(\text{from} = 1, \text{to} = 0, \text{length.out} = 1000)$ should be used for defining a sequence with 1000 steps. Some tuning of this sequence is required.

Value

A mrfout object with the following elements:
- theta: The estimated array of potentials.
- mrfi: The interaction structure considered.
- family: The parameter restriction family considered.
- method: The estimation method ("Stochastic Approximation").
- metrics: A data.frame containing the the euclidean distance between the sufficient statics computed for $Z$ and the current sample.

Note

Stochastic Approximation is called "Controllable Simulated Annealing" in some references.

Examples where Stochastic Approximation is used with MRFs are (Gimel'farb 1996), (Atchadé et al. 2013).
Author(s)

Victor Freguglia

References


See Also

A paper with detailed description of the package can be found at https://arxiv.org/abs/2006.00383

Examples

```r
set.seed(2)
fit1 <- fit_sa(Z_potts, mrfi(1), family = "oneeach", gamma_seq = seq(1, 0, length.out = 50))
# Estimated parameters
fit1$theta
# A visualization of estimated gradient norm over iterations.
plot(fit1$metrics, type = "l")

fit_sa(Z_potts, mrfi(1), family = "oneeach", gamma_seq = seq(1, 0, length.out = 50))
```

---

**hmrfout**

*MRF fitting functions output*

**Description**

MRF fitting functions output

**Usage**

```r
## S3 method for class 'hmrfout'
print(x, ...)

## S3 method for class 'hmrfout'
summary(object, ...)

## S3 method for class 'hmrfout'
plot(x, ...)
```
Arguments

x  a hmrfout object.

...  other arguments not used by this method.

object  a hmrfout object.

---

Description

Different parameter restrictions can be included in estimation processes to make sure mrfs can successfully include a wide range of model types in its inference functions.

For model identifiability, at least one linear restriction is necessary. mrfs always assume $\theta_{0,0,r} = 0$ for all relative positions $r$.

Additionally, each family of restrictions may introduce other restrictions:

'onepar'

This family assumes the model is defined by a single parameter by adding the restriction

$$\theta_{a,b,r} = \phi \times 1(a \neq b).$$

Here $1()$ denotes the indicator function. In words, the parameter must be the same value for any pair with different values and 0 for any equal-valued pair.

'oneeach'

Similar to 'onepar', parameters are 0 for equal-valued pairs and a constant for pairs with different values, but the constant may differ between different relative positions $r$:

$$\theta_{a,b,r} = \phi_r \times 1(a \neq b).$$

'absdif'

All parameters $\theta_{a,b,r}$ with the same absolute difference between $a$ and $b$ must be equal within each relative position $r$. (Note that 'absdif' is equal to 'oneeach' for binary images).

$$\theta_{a,b,r} = \sum_d \phi_{d,r} \times 1(|a - b| == d)$$

'dif'

The same as 'absdif', but parameters may differ between positive and negative differences.

$$\theta_{a,b,r} = \sum_d \phi_{d,r} \times 1(a - b == d)$$
'free'

No additional restriction, all parameters other than $\theta_{0,0,r}$ vary freely.

Author(s)

Victor Freguglia

See Also

vignette("mrf2d-family",package = "mrf2d")

A paper with detailed description of the package can be found at https://arxiv.org/abs/2006.00383

Description

The mrfi S4 class is a representation of the interaction structure for a spatially-stationary Markov Random Field.

The function mrfi() provides an interface for creation mrfi objects. A plot method is also available for visualization, as well as conversion methods like as.list and operators like +.

mrfi() creates an object of class mrfi based on a distance rule and optionally a list of relative positions. The argument max_norm and norm_type can be used to automatically include all positions within a "range" defined by the norm type chosen and distance using that norm.

A list of relative positions may also be included to specify sparse interaction structures, for example. Alternatively, rpositions() can be used to create a based exclusively on a list of relative positions.

Simple operations are provided to include (set union) new interacting positions to a mrfi object with the '+' operator and remove positions (set difference) with -. Individual positions can be included/excluded using length-2 vectors in the right hand side. Union and set difference of complete structures can also be computed by adding or subtracting two mrfi objects.

These operations deal with opposite directions filtering to avoid redundancy in the interaction structure.

Usage

mrfi(max_norm = 1, norm_type = "1", positions = NULL)

rpositions(positions)

## S3 method for class 'mrfi'
as.list(x, ...)

## S4 method for signature 'mrfi'
length(x)
## S4 method for signature 'mrfi,numeric,missing'
x[[i]]

## S4 method for signature 'mrfi,numeric,missing'
x[i]

## S4 method for signature 'mrfi,numeric'
e1 + e2

## S4 method for signature 'mrfi,numeric'
e1 - e2

## S4 method for signature 'mrfi,mrfi'
e1 + e2

## S4 method for signature 'mrfi,mrfi'
e1 - e2

mrfi_to_string(mrfi)

### Arguments

- `max_norm` a numeric value. All points with norm $\leq$ max_dist are included.
- `norm_type` a character indicating the norm type used. Possible values are "m", "1", "2", etc. See `norm` for details.
- `positions` a list of numeric vectors of length 2. Each vector corresponds to a relative position included.
- `x` `mrfi` object.
- `...` other arguments not used by this method.
- `i` vector of indexes to extract interacting positions.
- `e1, mrfi` A `mrfi` object.
- `e2` Either a second `mrfi` object or a length 2 numeric with the new relative position to include (+) or remove (-).

### Details

The interaction structure is defined by the list of relative positions in it. For a specific pixel, conditional to the values of pixels in these relative positions from it, its value is independent of any other pixel in the image.

The relative positions are identified by two integers $rx$ and $ry$ representing the "shift" in the $x$-axis and $y$-axis respectively. As an example: The relative position $(1,0)$ represents the pixel in the immediate right position, while $(-1,0)$ the left one.

Note that the inclusion of a relative position to the dependence also implies its opposite direction is not conditionally independent (commutativeness of dependence), but only one is included in the `mrfi` object.
To illustrate that, a nearest neighbor dependence structure can be specified by:
\[
mrfi(1)
\]
Note that it only includes the positions (1,0) and (0,1), but when visualizing it, for example, \texttt{mrf2d}
understands the opposite directions are also conditionally dependent, as in
\[
\text{plot(mrfi(1))}.
\]

**Value**

A \texttt{mrfi} object.

\texttt{as.list()}: converts the \texttt{mrfi} object to a list of interacting positions (list of length-2 vectors).

\texttt{[[]: converts to list and subsets it.}

\texttt{[:: subsets the \texttt{mrfi} object and returns another \texttt{mrfi} object.}

\texttt{+: computes the union of the interaction structure in a \texttt{mrfi} object with a numeric representing an}
additional position to include or another \texttt{mrfi} object.

**Slots**

\texttt{Rmat} A 2-column matrix where each row represents a relative position of interaction.

**Note**

If a position in \texttt{positions} is already included due to the \texttt{max_norm} and \texttt{norm_type} specification,
the second occurrence is ignored. The same is valid for repeated or opposite positions in \texttt{positions}.

**See Also**

A paper with detailed description of the package can be found at \url{https://arxiv.org/abs/2006.00383}

**Examples**

\[
\begin{align*}
\text{plot(mrfi(max_norm = 2, norm_type = "l"))} \\
\text{plot(mrfi(max_norm = 2, norm_type = "m"))} \\
\text{plot(mrfi(max_norm = 2, norm_type = "l", positions = list(c(4,4))))} \\
\text{as.list(mrfi(1))} \\
\text{mrfi(1)[[1]]} \\
\text{mrfi(2)[[1:3]]} \\
\text{mrfi(1)} \\
\text{rpositions(list(c(1,0), c(0,1)))} \\
\text{mrfi(2)} \\
\text{mrfi(2, norm_type = "m")} \\
\text{mrfi(1, positions = list(c(4,4), c(-4,4)))}
\end{align*}
\]

#Repeated positions are handled automatically
\[
\text{mrfi(1, positions = list(c(1,0), c(2,0)))}
\]
mrfout

```
mrfi(1) + c(2,0)
mrfi(1) - c(1,0)
mrfi(1) + mrfi(0, positions = list(c(2,0)))
mrfi(2) - mrfi(1)
```

---

**mrfout**  
*MRF fitting functions output*

---

**Description**

MRF fitting functions output

**Usage**

```r
## S3 method for class 'mrfout'
print(x, ...)

## S3 method for class 'mrfout'
summary(object, ...)

## S3 method for class 'mrfout'
plot(x, ...)
```

**Arguments**

- `x`: a `mrfout` object.
- `...`: other arguments not used by this method.
- `object`: a `mrfout` object.

---

**plot.mrfi**  
*Plotting of mrfi objects.*

---

**Description**

Plots a visual representation of the interaction structure described in a `mrfi` object. The black tile represents a reference pixel and gray tiles are shown in relative positions with dependent pixels.

A `ggplot` object is used, therefore, the user can load the `ggplot2` package and add more `ggplot` layers to freely customize the plot.

**Usage**

```r
## S3 method for class 'mrfi'
plot(x, include_axis = FALSE, include_opposite = TRUE, ...)
```
Arguments

x A mrfi object.

include_axis logical indicating whether the axis and grid lines are included. If FALSE theme_void() is added to the ggplot object.

include_opposite `logical' whether opposite directions should be included in the visualization of the dependence structure.

... other arguments not used by this method.

Details

The data.frame used for the ggplot call has columns names rx and ry representing the relative positions.

Value

A ggplot object using geom_tile() to represent interacting relative positions.

Author(s)

Victor Freguglia

Examples

plot(mrfi(1))

library(ggplot2)
plot(mrfi(1)) + geom_tile(fill = "red")
plot(mrfi(1)) + geom_tile(fill = "blue") + theme_void()

plot(mrfi(1)) + geom_text(aes(label = paste0("(",rx,"","ry,""))))

pl_mrf2d Pseudo-likelihood function for MRFs on 2d lattices

Description

Computes the pseudo-likelihood function of a Markov Random Field on a 2-dimensional lattice.

Usage

pl_mrf2d(Z, mrfi, theta, log_scale = TRUE)
Arguments

Z A matrix with integers in \{0,\ldots,C\}.

mrfi A mrfi object representing the interaction structure.

theta A 3-dimensional array describing potentials. Slices represent interacting positions, rows represent pixel values and columns represent neighbor values. As an example: theta[1,3,2] has the potential for the pair of values 0,2 observed in the second relative position of mrfi.

log_scale A logical value indicating whether the returned value should be in logarithmic scale.

Details

The pseudo-likelihood function is defined as the product of conditional probabilities of each pixel given its neighbors:

\[
\prod_i P(Z_i|Z_{N_i}, \theta).
\]

Value

A numeric with the pseudo-likelihood value.

Author(s)

Victor Freguglia

See Also

A paper with detailed description of the package can be found at https://arxiv.org/abs/2006.00383

Examples

pl_mrf2d(Z_potts, mrfi(1), theta_potts)

---

Description

Performs pixelwise updates based on conditional distributions to sample from a Markov random field.
Usage

```
rmrf2d(
  init_Z,
  mrfi,
  theta,
  cycles = 60,
  sub_region = NULL,
  fixed_region = NULL
)
```

Arguments

- **init_Z**
  One of two options:
  - A matrix object with the initial field configuration. Its values must be integers in \( \{0, \ldots, C\} \).
  - A length 2 numeric vector with the lattice dimensions.
- **mrfi**
  A `mrfi` object representing the interaction structure.
- **theta**
  A 3-dimensional array describing potentials. Slices represent interacting positions, rows represent pixel values and columns represent neighbor values. As an example: `theta[1,3,2]` has the potential for the pair of values 0,2 observed in the second relative position of `mrfi`.
- **cycles**
  The number of updates to be done (for each each pixel).
- **sub_region**
  NULL if the whole lattice is considered or a logical matrix with `TRUE` for pixels in the considered region.
- **fixed_region**
  NULL if the whole lattice is to be sampled or a logical matrix with `TRUE` for pixels to be considered fixed. Fixed pixels are not updated in the Gibbs Sampler.

Details

This function implements a Gibbs Sampling scheme to sample from a Markov random field by iteratively sampling pixel values from the conditional distribution

\[
P(Z_i|Z_{\neq i}, \theta).
\]

A cycle means exactly one update to each pixel. The order pixels are sampled is randomized within each cycle.

If `init_Z` is passed as a length 2 vector with lattice dimensions, the initial field is sampled from independent discrete uniform distributions in \( \{0, \ldots, C\} \). The value of C is obtained from the number of rows/columns of `theta`.

A MRF can be sampled in a non-rectangular region of the lattice with the use of the `sub_region` argument or by setting pixels to `NA` in the initial configuration `init_Z`. Pixels with `NA` values in `init_Z` are completely disconsidered from the conditional probabilities and have the same effect as setting `sub_region = is.na(init_Z)`. If `init_Z` has `NA` values, `sub_region` is ignored and a warning is produced.

A specific region can be kept constant during the Gibbs Sampler by using the `fixed_region` argument. Keeping a subset of pixels constant is useful when you want to sample in a specific region of the image conditional to the rest, for example, in texture synthesis problems.
Value
A matrix with the sampled field.

Note
As in any Gibbs Sampling scheme, a large number of cycles may be required to achieve the target distribution, specially for strong interaction systems.

Author(s)
Victor Freguglia

See Also
rmrf2d_mc for generating multiple points of a Markov Chain to be used in Monte-Carlo methods.

Examples

```r
# Sample using specified lattice dimension
Z <- rmrf2d(c(150,150), mrfi(1), theta_potts)

# Sample using initial configuration
Z2 <- rmrf2d(Z, mrfi(1), theta_potts)

# View results
dplot(Z)
dplot(Z2)

# Using sub-regions
subreg <- matrix(TRUE, 150, 150)
subreg <- abs(row(subreg) - 75) + abs(col(subreg) - 75) <= 80
# view the sub-region
dplot(subreg)
Z3 <- rmrf2d(c(150,150), mrfi(1), theta_potts, sub_region = subreg)
dplot(Z3)

# Using fixed regions
fixreg <- matrix(as.logical(diag(150)), 150, 150)
# Set initial configuration: diagonal values are 0.
init_Z4 <- Z
init_Z4[fixreg] <- 0
Z4 <- rmrf2d(init_Z4, mrfi(1), theta_potts, fixed_region = fixreg)
dplot(Z4)

# Combine fixed regions and sub-regions
Z5 <- rmrf2d(init_Z4, mrfi(1), theta_potts,
```
\texttt{rmrf2d\_mc}

\textbf{Markov Chain sampling of MRFs for Monte-Carlo methods}

\textbf{Description}

Generates a Markov Chain of random fields and returns the sufficient statistics for each of the observations.

This function automatizes the process of generating a random sample of MRFs to be used in Monte-Carlo methods by wrapping \texttt{rmrf2d} and executing it multiple times while storing sufficient statistics instead of the entire lattice.

\textbf{Usage}

\texttt{rmrf2d\_mc(init\_Z, mr\texttt{fi}, theta, family, nmc = 100, burnin = 100, cycles = 4)}

\textbf{Arguments}

- \texttt{init\_Z}: One of two options:
  - A matrix object with the initial field configuration. Its values must be integers in \{0,...,C\}.
  - A length 2 numeric vector with the lattice dimensions.
- \texttt{mr\texttt{fi}}: A \texttt{mrfi} object representing the interaction structure.
- \texttt{theta}: A 3-dimensional array describing potentials. Slices represent interacting positions, rows represent pixel values and columns represent neighbor values. An example: \texttt{theta[1,3,2]} has the potential for the pair of values 0,2 observed in the second relative position of \texttt{mr\texttt{fi}}.
- \texttt{family}: The family of parameter restrictions to potentials. Families are: 'onepar', 'oneeach', 'absdif', 'dif' or 'free'. See \texttt{mrf2d\_family}.
- \texttt{nmc}: Number of samples to be stored.
- \texttt{burnin}: Number of cycles iterated before start collecting sufficient statistics.
- \texttt{cycles}: Number of cycles between collected samples.

\textbf{Value}

A matrix where each row contains the vector of sufficient statistics for an observation.

\textbf{Note}

Fixed regions and incomplete lattices are not supported.
**smr_array**

**Author(s)**
Victor Freguglia

**Examples**

```r
r mf 2d mc(c(80, 80), mrfi(1), theta_potts, family = "oneeach", nmc = 8)
```

---

**Description**

`smr_array` creates a vector containing only the free parameters from an array given a restriction `family`. `expand_array` is the reverse operation, expanding a complete array from the vector of sufficient statistics.

**Usage**

```r
smr_array(theta, family)
expand_array(theta_vec, family, mrfi, C)
```

**Arguments**

- `theta`: A 3-dimensional array describing potentials. Slices represent interacting positions, rows represent pixel values and columns represent neighbor values. As an example: `theta[1,3,2]` has the potential for the pair of values 0,2 observed in the second relative position of `mrfi`.
- `family`: The family of parameter restrictions to potentials. Families are: 'onepar', 'oneeach', 'absdif', 'dif' or 'free'. See `mrf2d familia`.
- `theta_vec`: A numeric vector with the free parameters of a potential array. It's dimension depends on the restriction `family`, `C` and the number of interacting positions on `mrfi`.
- `mrfi`: A `mrfi` object representing the interaction structure.
- `C`: The maximum value of the field.

**Details**

The order the parameters appear in the summarized vector matches the order in `smr_stat()`.  

**Value**

`smr_array` returns a numeric vector with the free parameters of `theta`.  
`expand_array` returns a three-dimensional array of potentials.
Author(s)
Victor Freguglia

See Also
A paper with detailed description of the package can be found at https://arxiv.org/abs/2006.00383

Examples

```r
smr_array(theta_potts, "onepar")
smr_array(theta_potts, "oneeach")

expand_array(0.99, family = "onepar", mrfi = mrfi(1), C = 2)
expand_array(c(0.1, 0.2), family = "oneeach", mrfi = mrfi(1), C = 3)
```

---

smr_stat Summary Statistics

Description
Computes the summary count statistics of a field given an interaction structure and a restriction family.

- cohist() computes the co-occurrence histogram.
- smr_stat() computes the co-occurrence histogram, then converts it into a vector of sufficient statistics given a family of restrictions.

Usage

```r
smr_stat(Z, mrfi, family)

cohist(Z, mrfi)
```

Arguments

- **Z** A matrix object containing the observed MRF. NA values can be used to create a subregion of the lattice for non-rectangular data.
- **mrfi** A mrfi object representing the interaction structure.
- **family** The family of parameter restrictions to potentials. Families are: 'onepar', 'oneeach', 'absdif', 'dif' or 'free'. See mrf2d-family.

Details

The order the summarized counts appear in the summary vector matches the order in smr_array().
**Value**

A numeric vector with the summarized counts.

An array representing the co-occurrence histogram of \( Z \) in the relative positions contained in \( \text{mrfi} \).

Each row and column corresponds a pair of values in \((0, \ldots, C)\) and each slice corresponds to

**Author(s)**

Victor Freguglia

**See Also**


**Examples**

```r
smr_stat(Z_potts, mrfi(1), "onepar")
smr_stat(Z_potts, mrfi(1), "oneeach")

cohist(Z_potts, mrfi(1))
```

---

<table>
<thead>
<tr>
<th>Z_potts</th>
<th>Example objects from mrf2d</th>
</tr>
</thead>
</table>

**Description**

\( Z_{\text{potts}} \) and \( \theta_{\text{potts}} \) are example objects for \textit{mrf2d}.

\( Z_{\text{potts}} \) is a matrix object containing an observed lattice of a 3 color (\( C = 2 \)) Potts model.

\( \theta_{\text{potts}} \) is the parameter array used to sample it, it consists of a configuration with one parameter (-1,0) and two relative positions (to be used with a nearest-neighbor structure).

**Author(s)**

Victor Freguglia

**Examples**

```r
theta_potts
dplot(Z_potts)
```
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